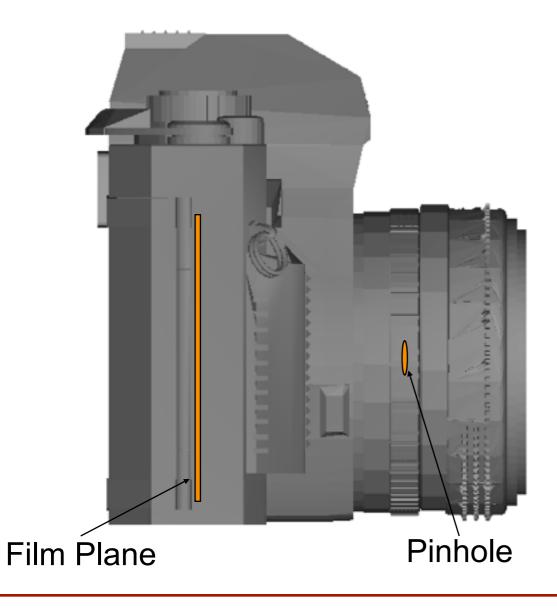
Connelly Barnes

CS 4810: Graphics

Acknowledgment: slides by Jason Lawrence, Misha Kazhdan, Allison Klein, Tom Funkhouser, Adam Finkelstein and David Dobkin

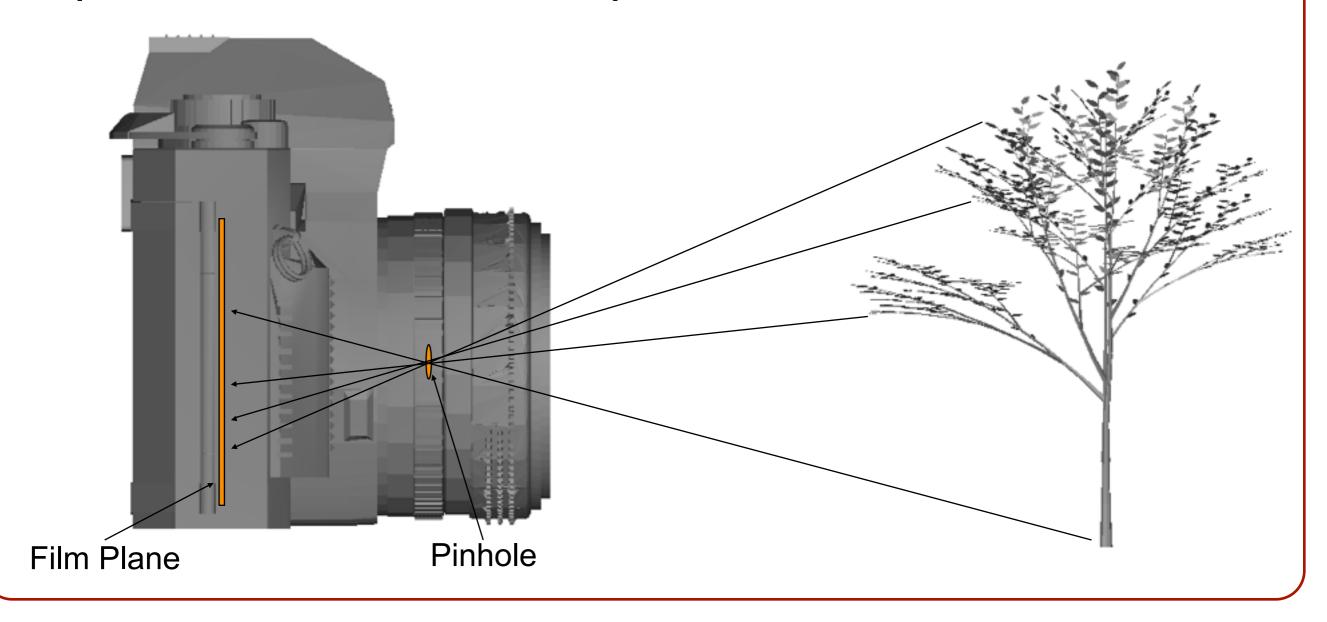
Traditional Pinhole Camera

The film sits behind the pinhole of the camera.



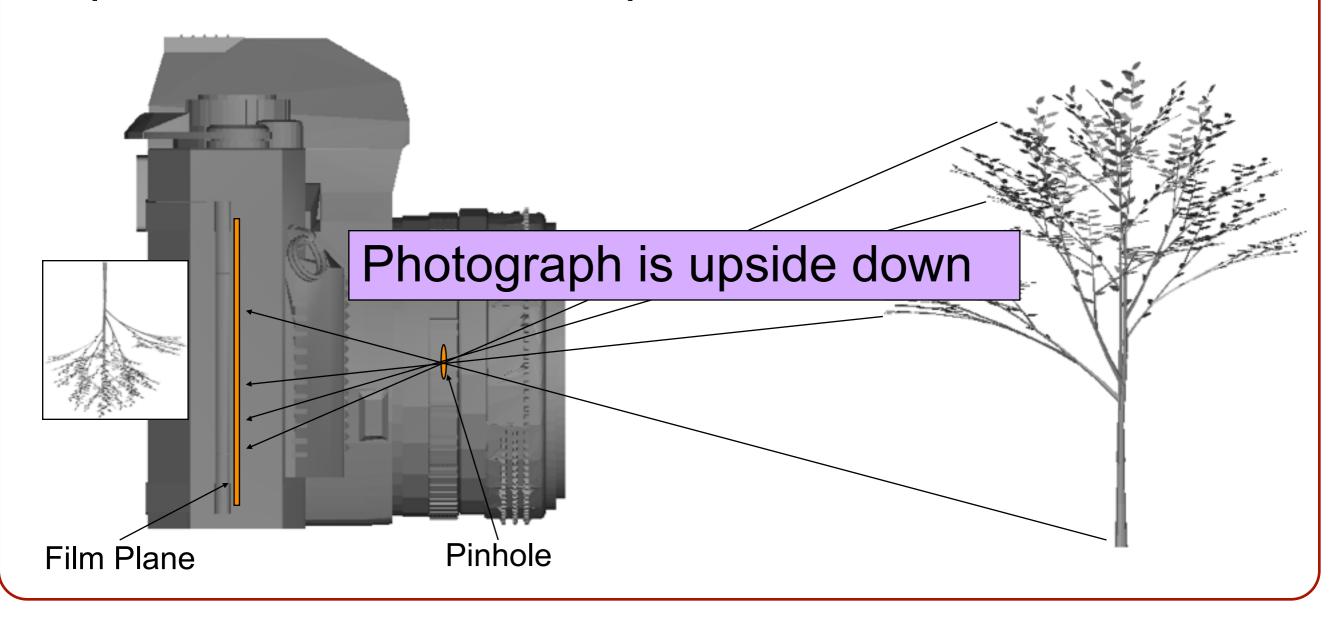
Traditional Pinhole Camera

- The film sits behind the pinhole of the camera.
- Rays come in from the outside, pass through the pinhole, and hit the film plane.



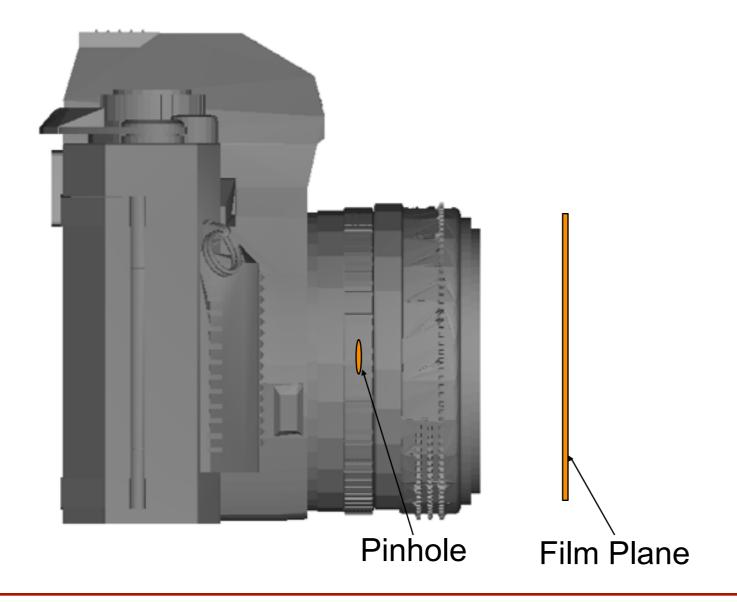
Traditional Pinhole Camera

- The film sits behind the pinhole of the camera.
- Rays come in from the outside, pass through the pinhole, and hit the film plane.



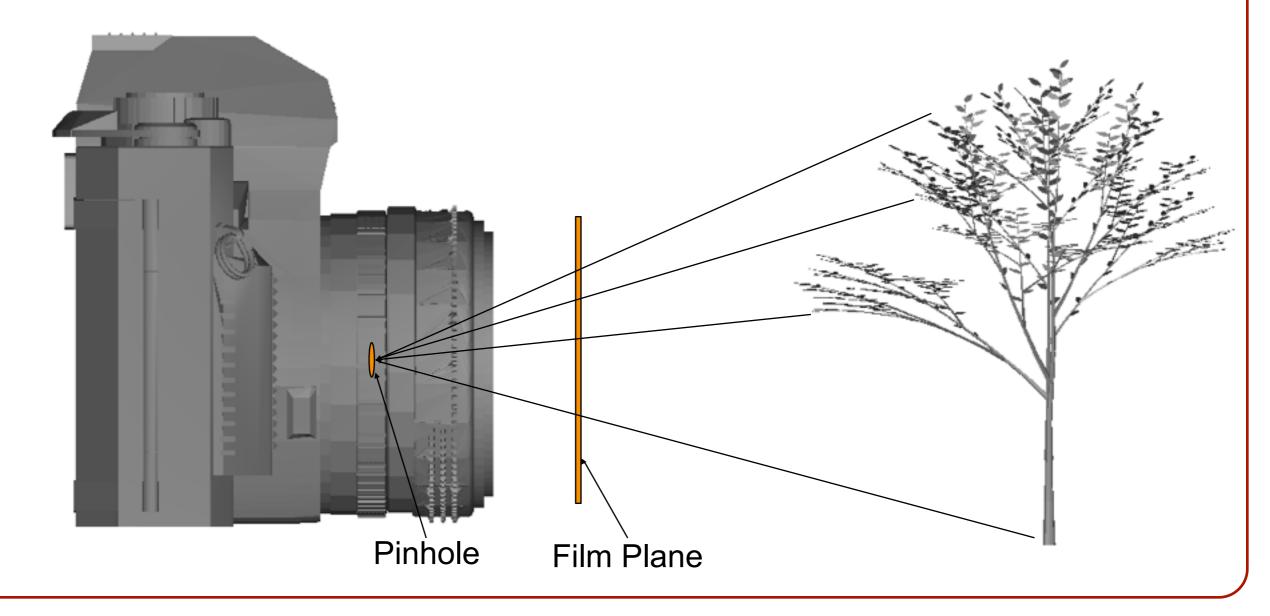
Virtual Camera

• The film sits in front of the pinhole of the camera.



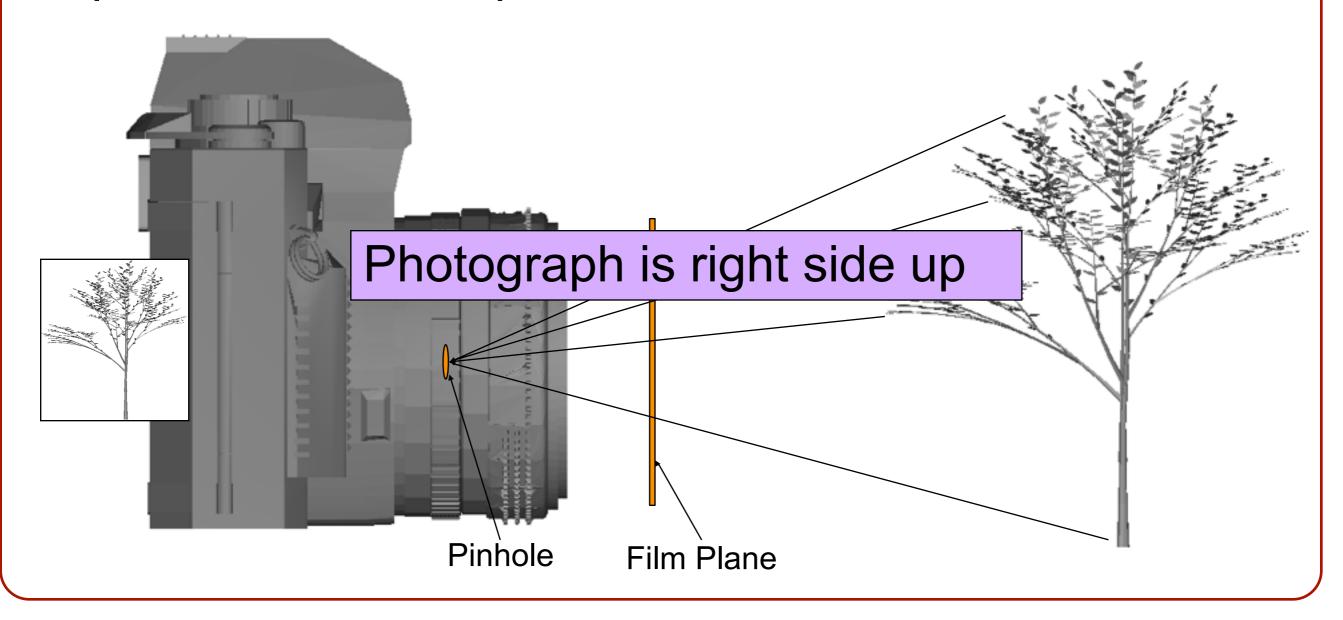
Virtual Camera

- The film sits in front of the pinhole of the camera.
- Rays come in from the outside, pass through the film plane, and hit the pinhole.



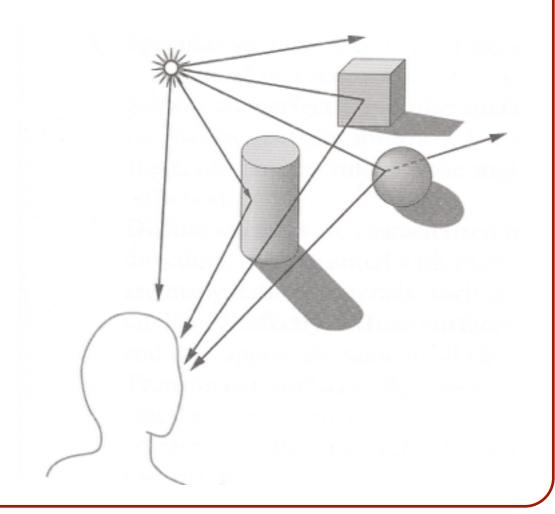
Virtual Camera

- The film sits in front of the pinhole of the camera.
- Rays come in from the outside, pass through the film plane, and hit the pinhole.



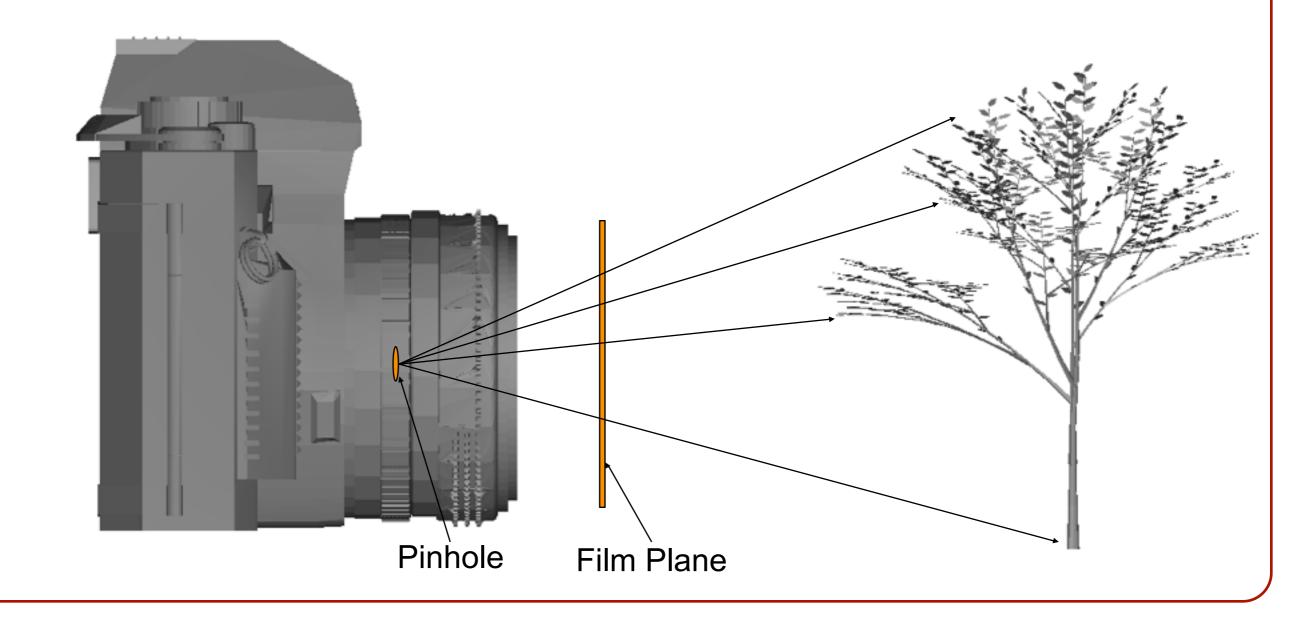
Overview

Ray CastingoWhat do we see?oHow does it look?

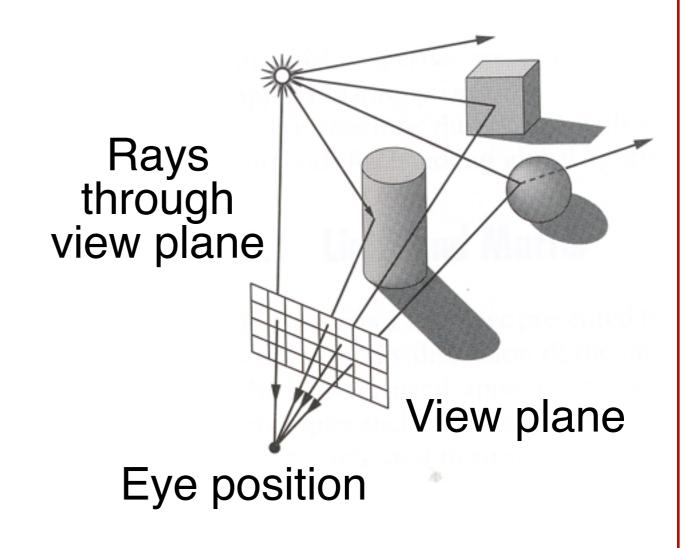


- Rendering model
- Intersections with geometric primitives
 oSphere
 oTriangle
- Acceleration techniques
 - oBounding volume hierarchies
 - oSpatial partitions
 - »Uniform grids
 - »Octrees
 - »BSP trees

 We invert the process of image generation by sending rays <u>out</u> from the pinhole, and then we find the first intersection of the ray with the scene.

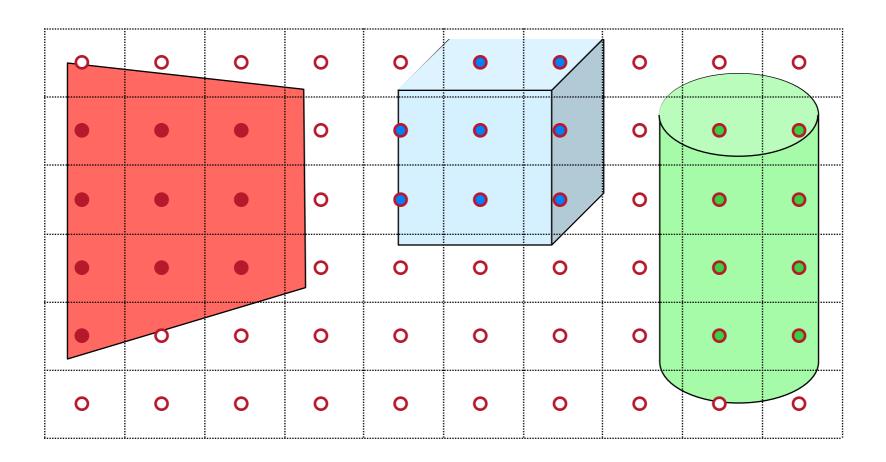


 The color of each pixel on the view plane depends on the radiance emanating from visible surfaces



For each sample ...

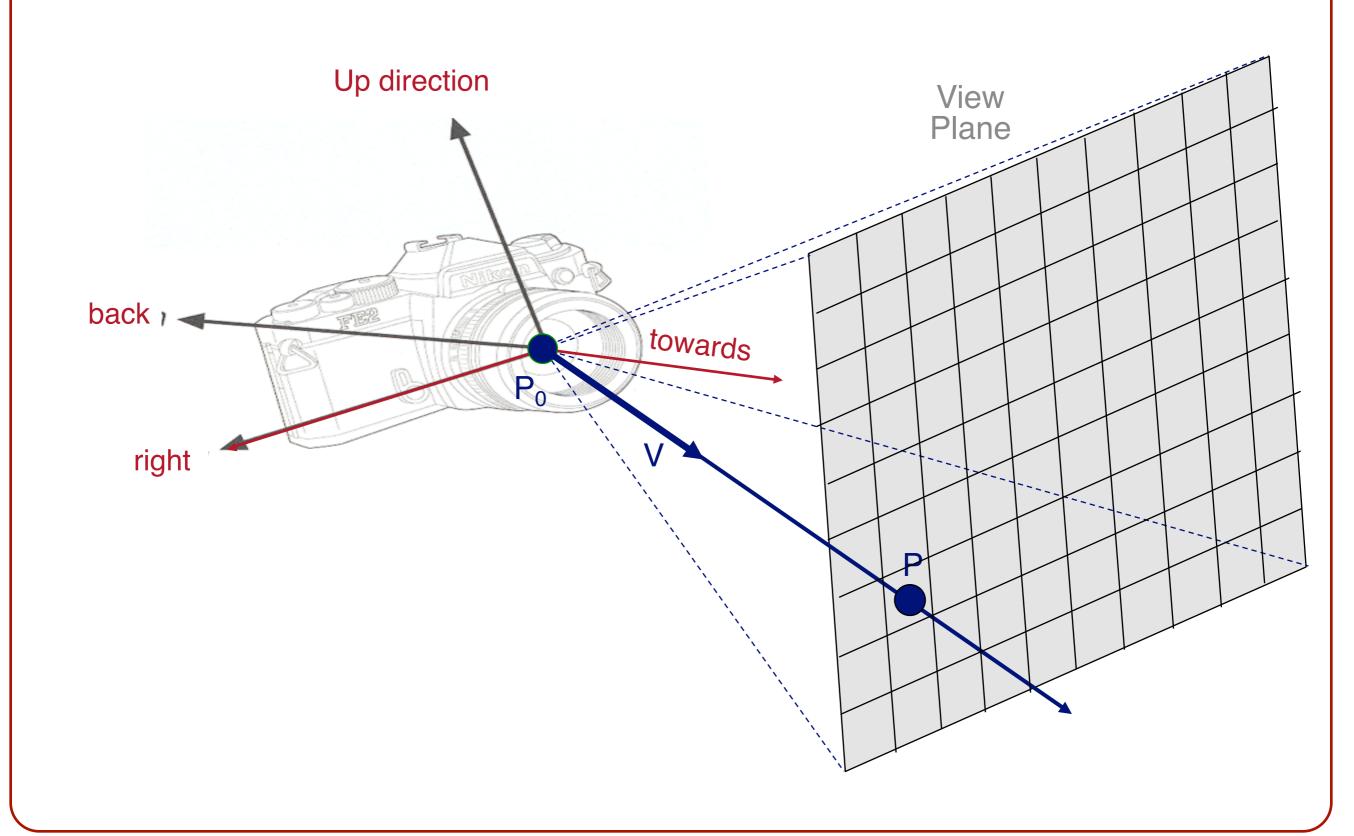
oConstruct ray from eye position through view plane
oFind <u>first</u> surface intersected by ray through pixel
oCompute color sample based on surface radiance

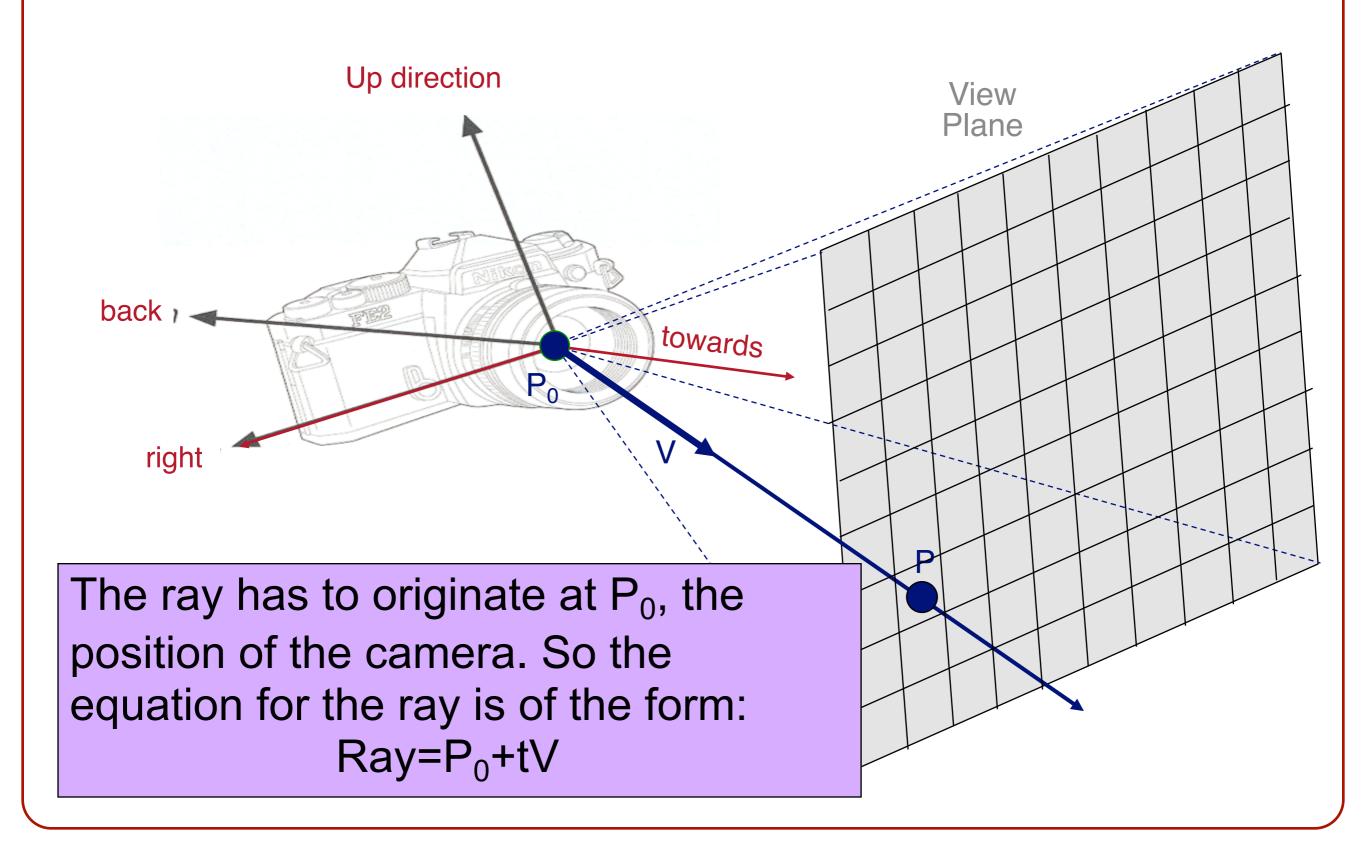


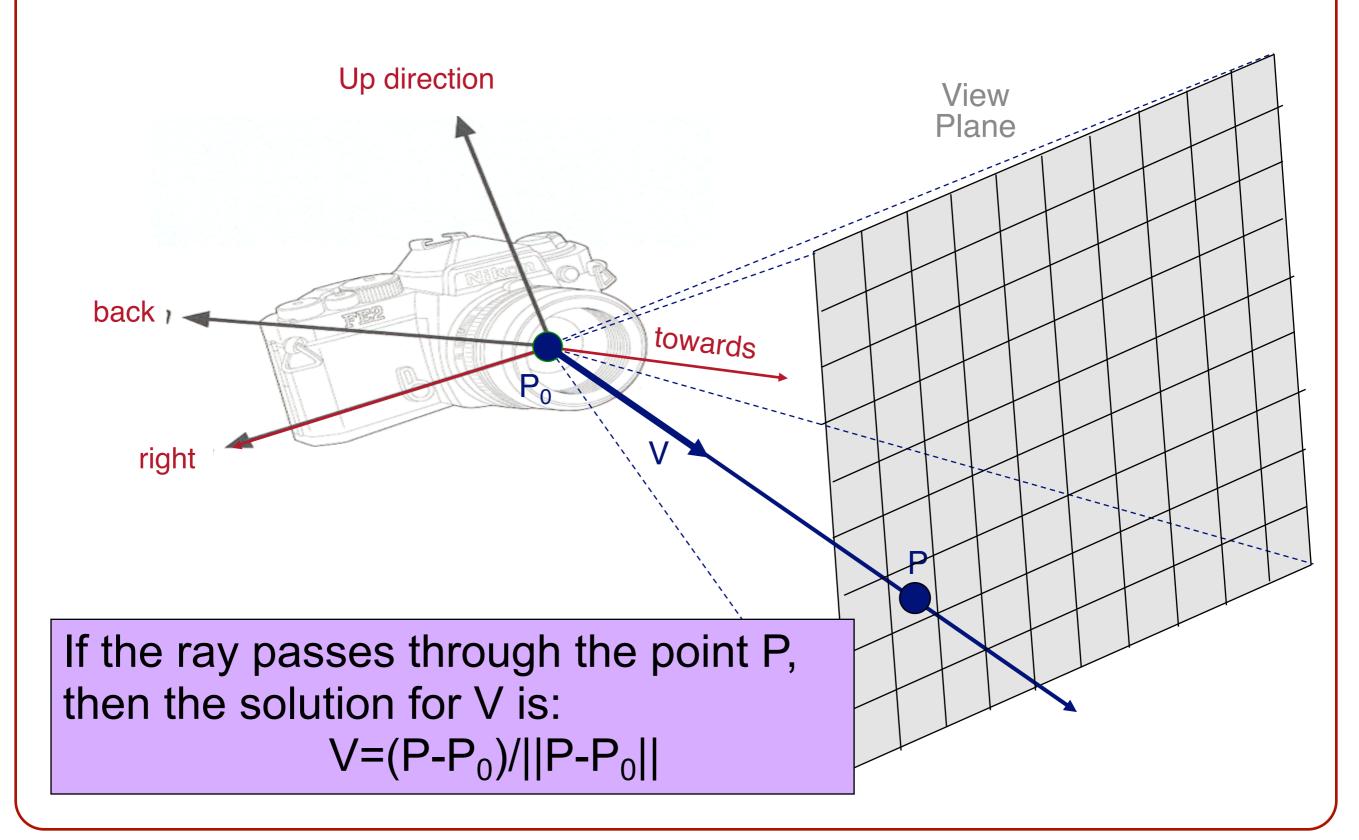
Simple implementation:

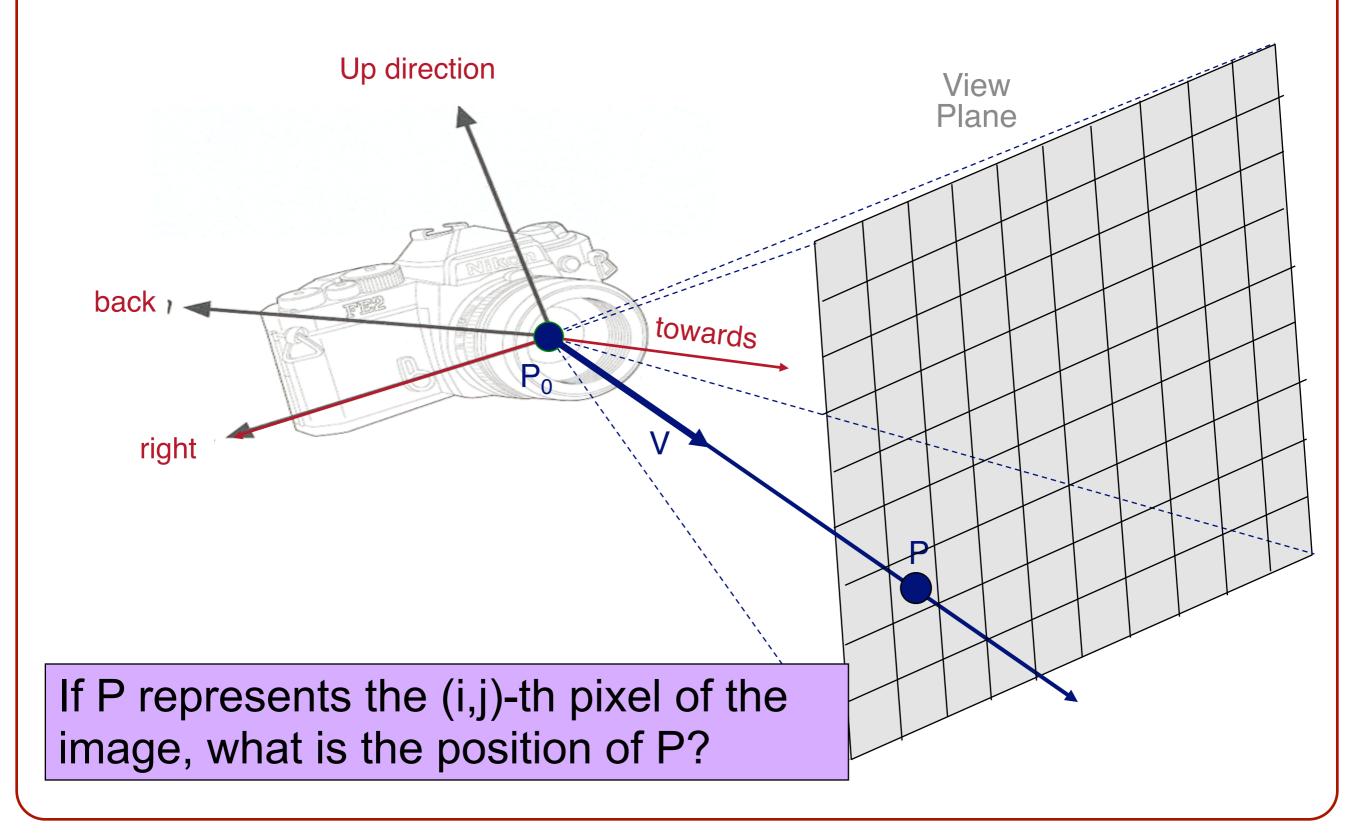
```
Image RayCast(Camera camera, Scene scene, int width, int height)
{
    Image image = new Image(width, height);
    for (int i = 0; i < width; i++) {
        for (int j = 0; j < height; j++) {
            Ray ray = ConstructRayThroughPixel(camera, i, j);
            Intersection hit = FindIntersection(ray, scene);
            image[i][j] = GetColor(hit);
        }
    }
    return image;
</pre>
```

- Where are we looking?
- What are we seeing?
- What does it look like?





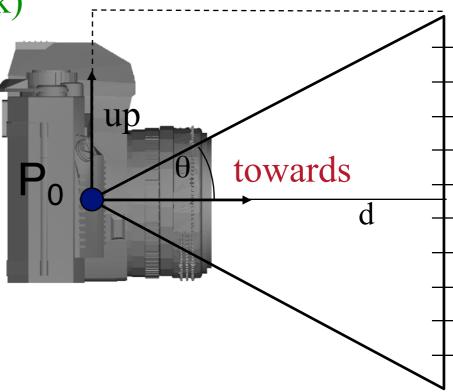




2D Example: Side view of camera at P₀
 oWhat is the position of the *i*-th pixel P[i]?

 θ = frustum half-angle (given), or field of view

d = distance to view plane (arbitrary = you pick)



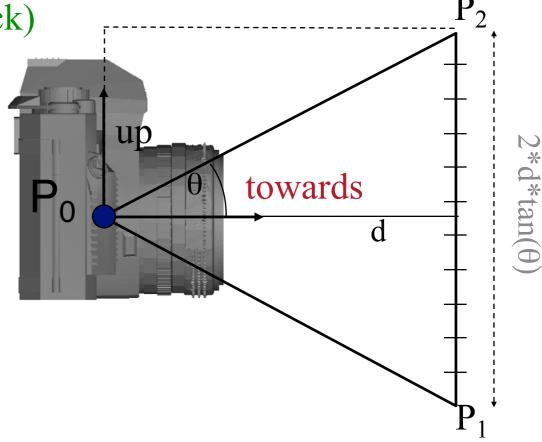
2D Example: Side view of camera at P₀
 oWhat is the position of the *i*-th pixel P[i]?

 θ = frustum half-angle (given), or field of view

d = distance to view plane (arbitrary = you pick)

 $P_1 = P_0 + d*towards - d*tan(\theta)*up$

 $P_2 = P_0 + d*towards + d*tan(\theta)*up$



2D Example: Side view of camera at P₀
 oWhat is the position of the *i*-th pixel?

 θ = frustum half-angle (given), or field of view

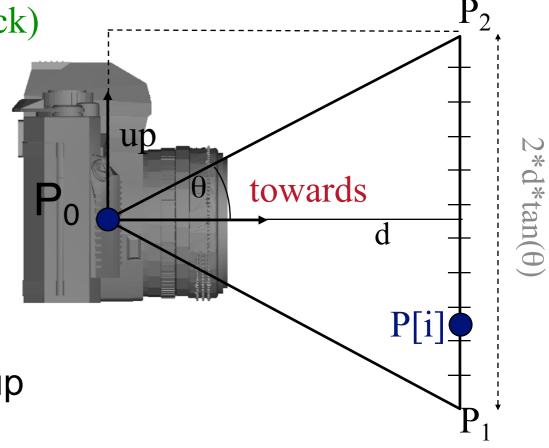
d = distance to view plane (arbitrary = you pick)

$$P_1 = P_0 + d*towards - d*tan(\theta)*up$$

$$P_2 = P_0 + d*towards + d*tan(\theta)*up$$

$$P[i] = P_1 + ((i+0.5)/height)*(P_2-P_1)$$

= $P_1 + ((i+0.5)/height)*2*d*tan(\theta)*up$



2D Example:

oThe ray passing through the *i*-th pixel is defined by:

 $Ray=P_0+tV$

Where:

oP₀ is the camera position

oV is the direction to the i-th

pixel: $V=(P[i]-P_0)/||P[i]-P_0||$

oP[i] is the *i*-th pixel location:

 (P_2-P_1)

 $P[i] = P_1 + ((i+0.5)/height)*(P_2-P_1)$

 oP_1 and P_2 are the endpoints of the view plane:

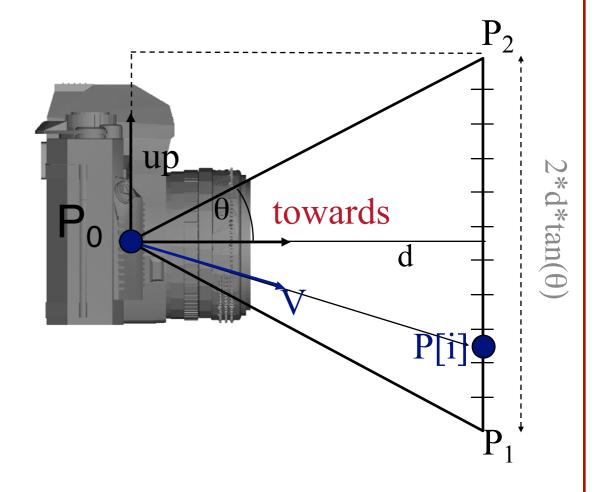
$$P_1 = P_0 + d*towards - d*tan(\theta)*up$$

$$P_2 = P_0 + d*towards + d*tan(\theta)*up$$

2D implementation:

```
Image RayCast(Camera camera, Scene scene, int width, int height)
{
    Image image = new Image(width, height);
    for (int i = 0; i < height; i++) {
        Ray ray = ConstructRayThroughPixel(camera, i, height);
        Intersection hit = FindIntersection(ray, scene);
        image[i][height] = GetColor(hit);
    }
    return image;
}</pre>
```

Figuring out how to do this in 3D is assignment 2



Simple implementation:

```
Image RayCast(Camera camera, Scene scene, int width, int height)
    Image image = new Image(width, height);
    for (int i = 0; i < width; i++) {
         for (int j = 0; j < \text{height}; j++) {
             Ray ray = ConstructRayThroughPixel(camera, i, j);
              Intersection hit = FindIntersection(ray, scene);
             image[i][j] = GetColor(hit);
    return image;
```

Simple implementation:

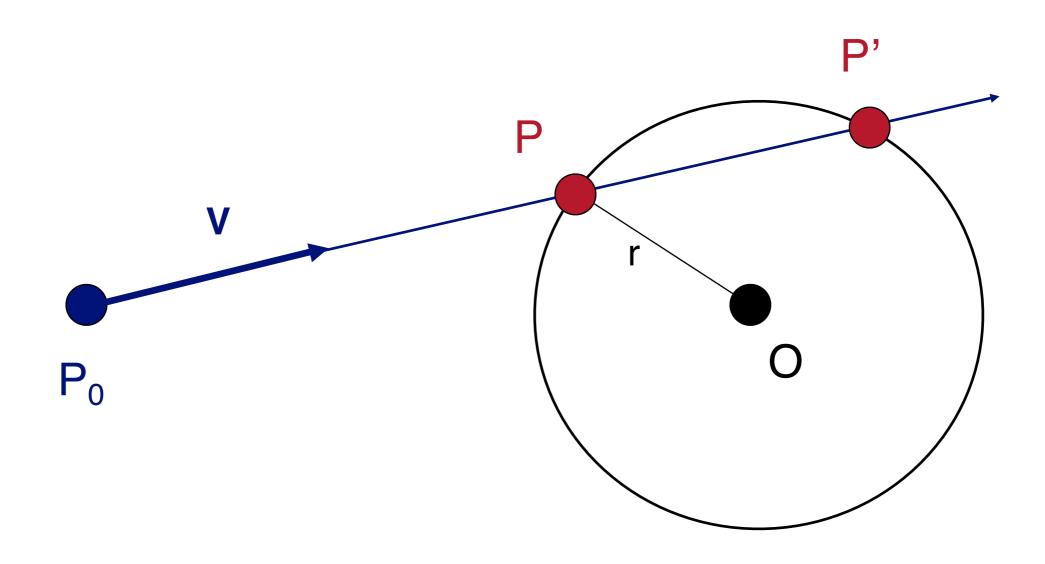
```
Image RayCast(Camera camera, Scene scene, int width, int height)
    Image image = new Image(width, height);
    for (int i = 0; i < width; i++) {
         for (int j = 0; j < \text{height}; j++) {
             Ray ray = ConstructRayThroughPixel(camera, i, j);
              Intersection hit = FindIntersection(ray, scene);
             image[i][j] = GetColor(hit);
    return image;
```

Ray-Scene Intersection

- Intersections with geometric primitives
 oSphere
 - oTriangle
- Acceleration techniques
 - oBounding volume hierarchies
 - oSpatial partitions
 - »Uniform (Voxel) grids
 - »Octrees
 - »BSP trees

Ray: $P = P_0 + tV$

Sphere: $IP - Ol^2 - r^2 = 0$



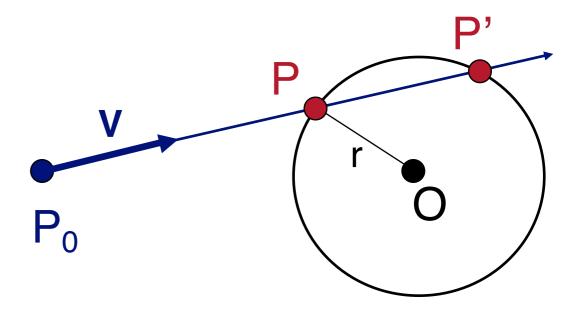
Ray: $P = P_0 + tV$

Sphere: $IP - Ol^2 - r^2 = 0$

Algebraic Method

Substituting for P, we get:

$$IP_0 + tV - OI^2 - r^2 = 0$$



Ray: $P = P_0 + tV$

Sphere: $IP - OI^2 - r^2 = 0$

Algebraic Method

Substituting for P, we get:

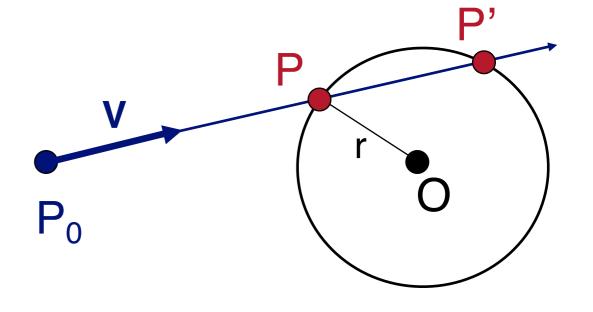
$$|P_0 + tV - O|^2 - r^2 = 0$$

Solve quadratic equation:

$$at^2 + bt + c = 0$$

where:

Discard hits with negative t (intersected behind ray origin).



Ray: $P = P_0 + tV$

Sphere: $IP - Ol^2 - r^2 = 0$

Algebraic Method

Substituting for P, we get:

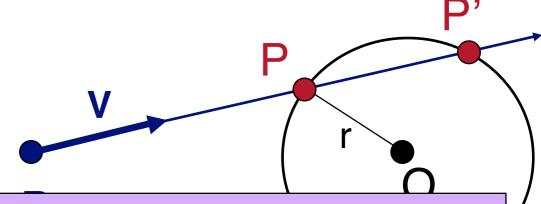
$$|P_0 + tV - O|^2 - r^2 = 0$$

Solve quadratic equation:

$$at^2 + bt + c = 0$$

where:

$$a = 1$$



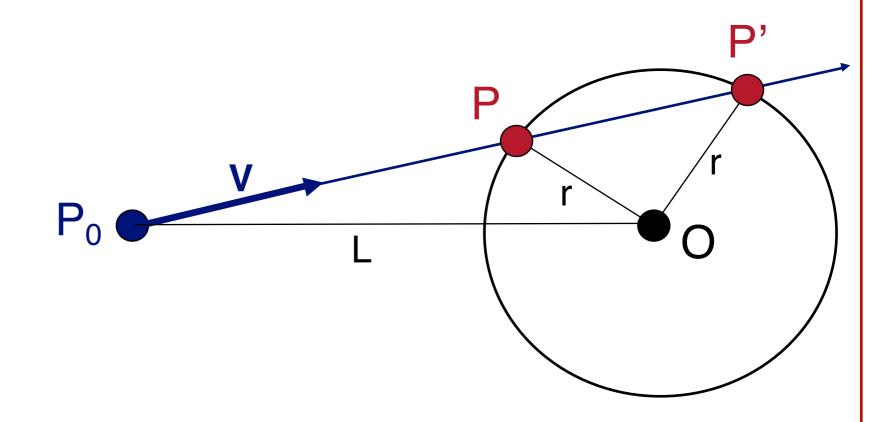
Generally, there are two solutions to the quadratic equation, giving rise to points P and P'. You want to return the first hit (with positive t).

Ray: $P = P_0 + tV$

Sphere: $IP - Ol^2 - r^2 = 0$

 $L = O - P_0$

Geometric Method

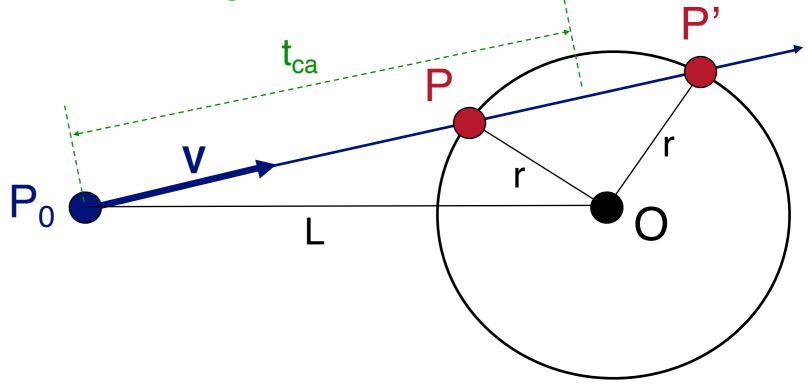


Ray: $P = P_0 + tV$

Sphere: $IP - Ol^2 - r^2 = 0$

Geometric Method

$$L = O - P_0$$



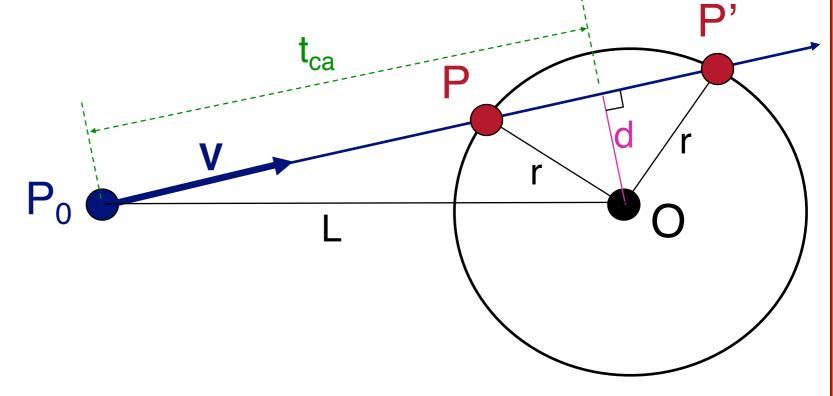
Ray: $P = P_0 + tV$

Sphere: $IP - OI^2 - r^2 = 0$

Geometric Method

$$L = O - P_0$$

$$d^2 = L \cdot L - t_{ca}^2$$
if $(d^2 > r^2)$ return 0



Ray: $P = P_0 + tV$

Sphere: $IP - Ol^2 - r^2 = 0$

Geometric Method

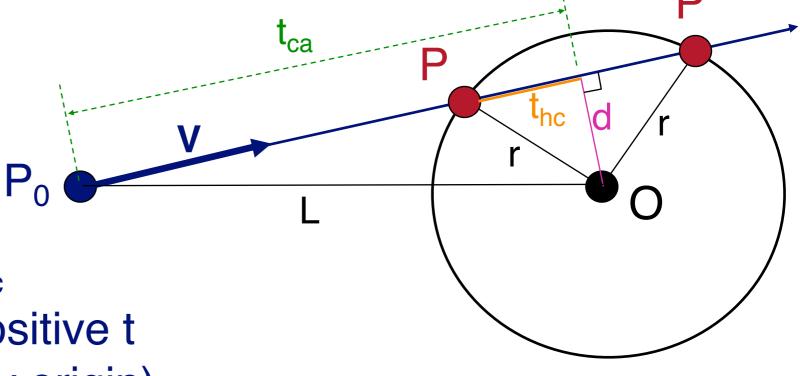
$$L = O - P_0$$

$$d^2 = L \cdot L - t_{ca}^2$$
if (d² > r²) return 0

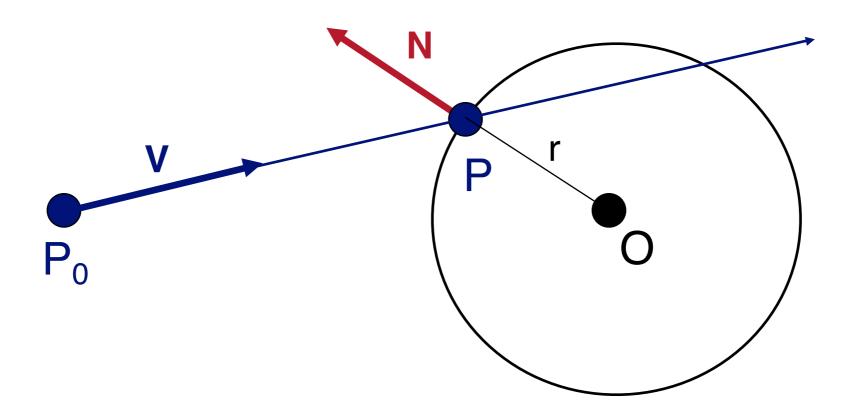
$$t_{hc} = sqrt(r^2 - d^2)$$

 $t = t_{ca} - t_{hc}$ and $t_{ca} + t_{hc}$

Return first hit with positive t (ignore hits behind ray origin).

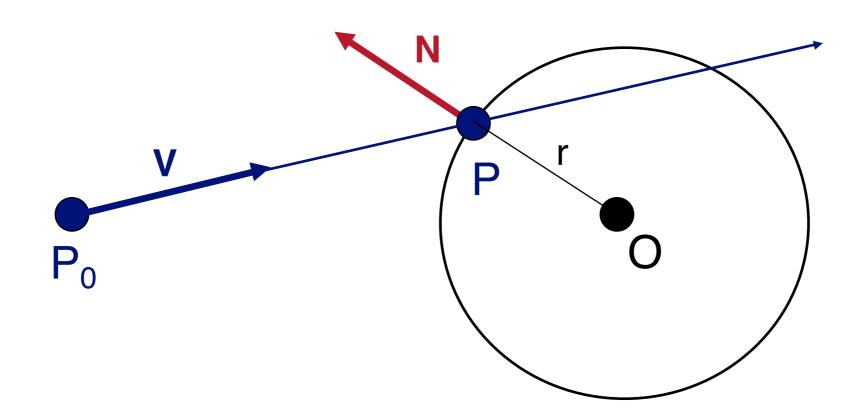


 Need normal vector at intersection for lighting calculations



 Need normal vector at intersection for lighting calculations

$$N = (P - O) / IIP - OII$$



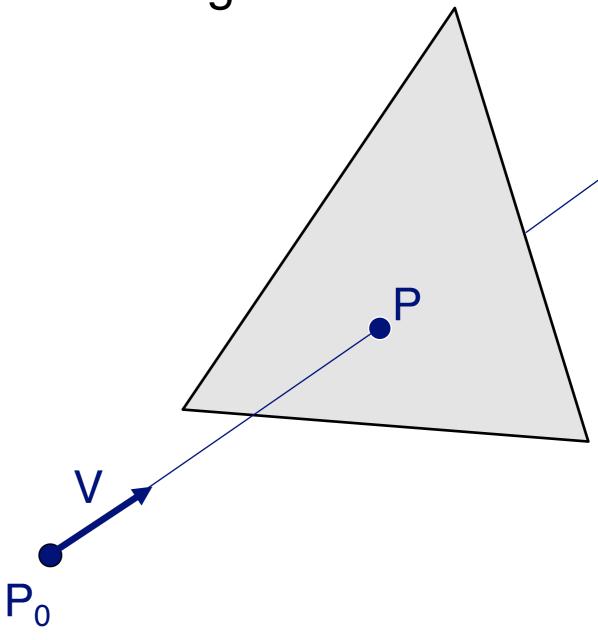
Ray-Scene Intersection

- Intersections with geometric primitives
 - **o**Sphere
 - » Triangle
- Acceleration techniques
 - oBounding volume hierarchies
 - oSpatial partitions
 - »Uniform grids
 - »Octrees
 - »BSP trees

Ray-Triangle Intersection

• First, intersect ray with plane

• Then, check if point is inside triangle



Ray-Plane Intersection

Ray: $P = P_0 + tV$

Plane: $P \cdot N + d = 0$

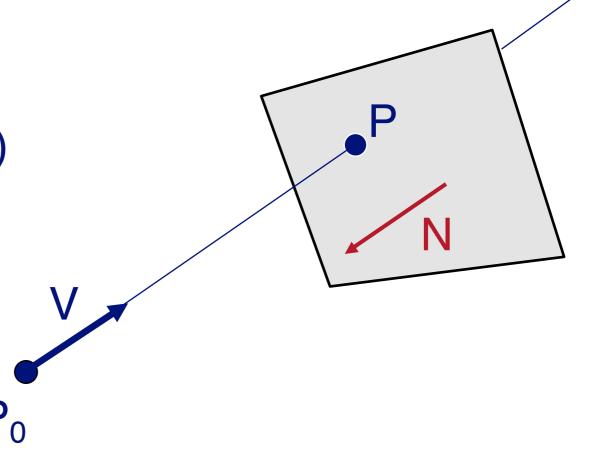
Substituting for P, we get:

$$(P_0 + tV) \cdot N + d = 0$$

Solution:

$$t = -(P_0 \cdot N + d) / (V \cdot N)$$

Algebraic Method



Ray-Triangle Intersection I

Check if point is inside triangle algebraically

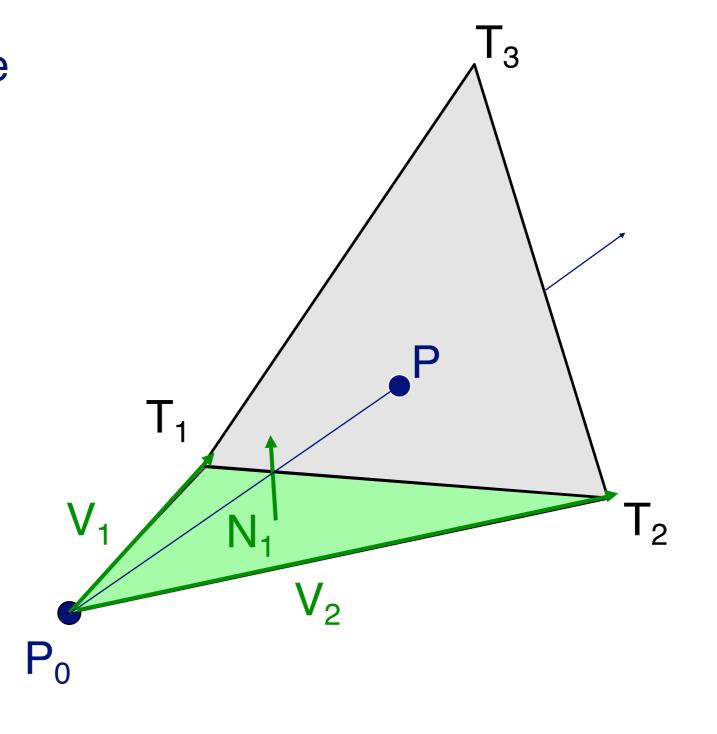
```
For each side of triangle V_1 = T_1 - P_0

V_2 = T_2 - P_0

N_1 = V_2 \times V_1

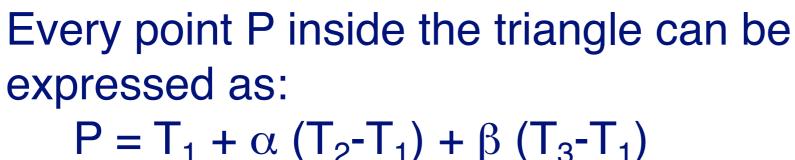
if ((P - P_0) \cdot N_1 < 0)

return FALSE;
```



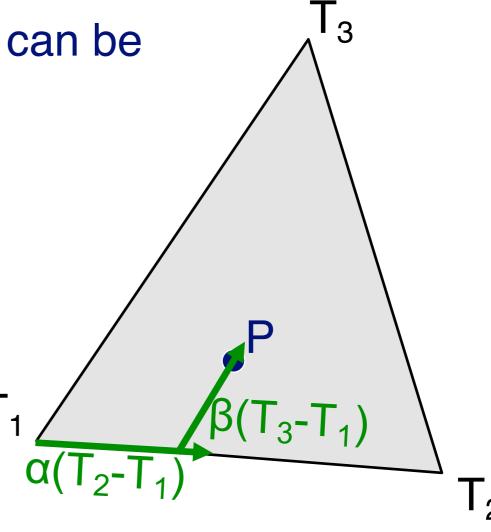
Ray-Triangle Intersection II

Check if point is inside triangle parametrically



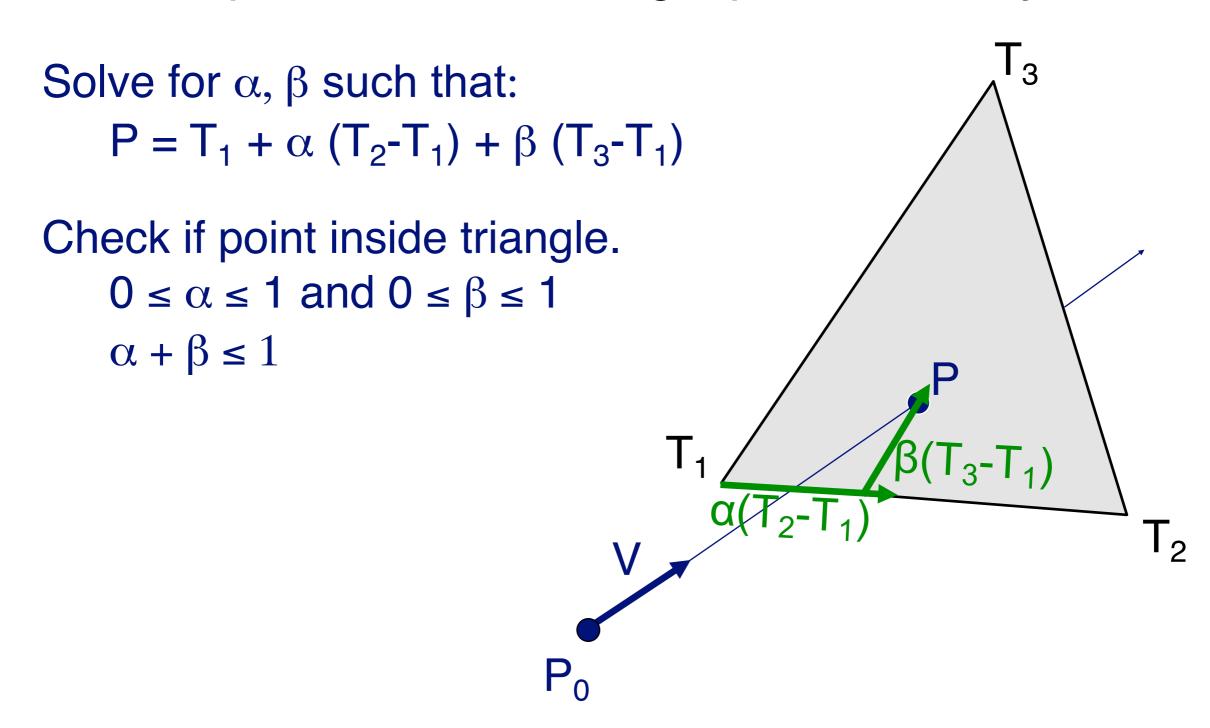
where:

$$0 \le \alpha \le 1$$
 and $0 \le \beta \le 1$
 $\alpha + \beta \le 1$



Ray-Triangle Intersection II

Check if point is inside triangle parametrically



Other Ray-Primitive Intersections

- Cone, cylinder, ellipsoid:
 oSimilar to sphere
- Box
 oIntersect 3 front-facing planes, return closest
- Convex polygon
 oSame as triangle (check point-in-polygon algebraically)
- Concave polygon
 oSame plane intersection
 oMore complex point-in-polygon test

Ray-Scene Intersection

Find intersection with front-most primitive in group

```
Intersection FindIntersection(Ray ray, Scene scene)
    \min \ t = \infty
    min shape = NULL
    For each primitive in scene {
         t = Intersect(ray, primitive);
         if (t > 0 \text{ and } t < \min t) then
              min_shape = primitive
              \min t = t
    return Intersection(min t, min shape)
```

Next Lecture

- Intersections with geometric primitives
 oSphere
 oTriangle
- » Acceleration techniques
 - oBounding volume hierarchies
 - oSpatial partitions
 - »Uniform grids
 - »Octrees
 - »BSP trees